



National Aeronautics and Space Administration

UAS in the NAS Flight Test Series 3 Overview



7 July 2015



Overview

- Goals/Objectives
- Participants
- Test Configurations
 - Config 1: Scripted Encounters
 - Config 2: Full Mission
- Future Testing/Schedule

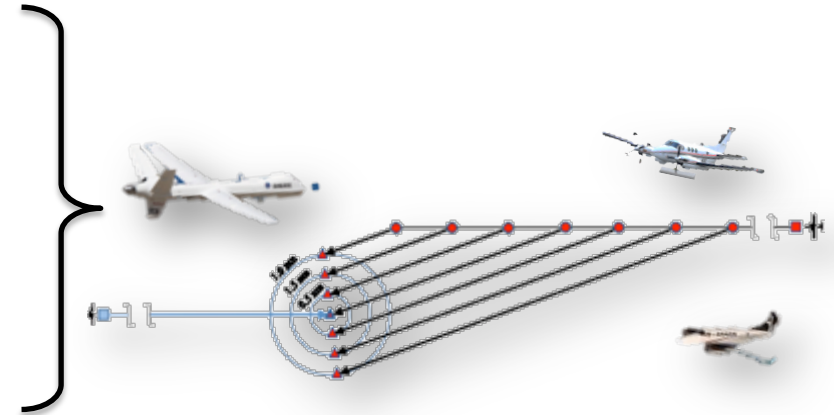


Flight Test 3 Overview

Top Level Research Goals

Top Level Research Goals:

- Validate results previously collected during project simulations with live data
 - Sensor performance, uncertainty
 - State data uncertainty
 - Wind compensation
- Evaluate TCAS II/SS interoperability
- Test fully integrated system in a relevant live test environment
 - HSI Proof of Concept GCS and pilot guidance displays
 - CNPC performance
- Inform final DAA and C2 MOPS
- Reduce risk for Flight Test Series 4
 - More complex multi-intruder scenarios



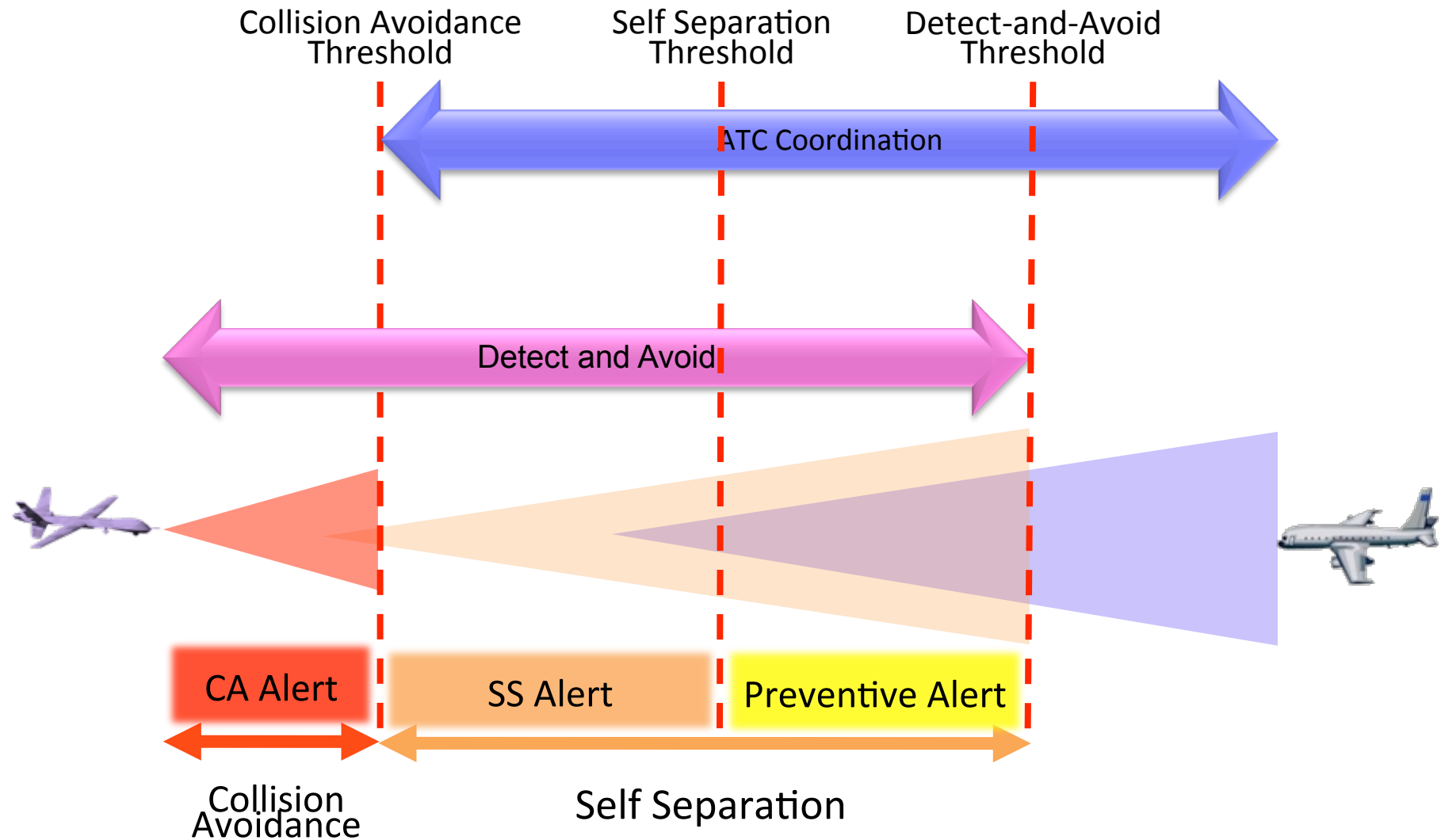
Full Mission Scenario Evaluations

- Live Ownship (Surrogate UA)
- Live and Virtual Intruders
- Representative Operational Mission
- UAS Pilot Participants using RGCS



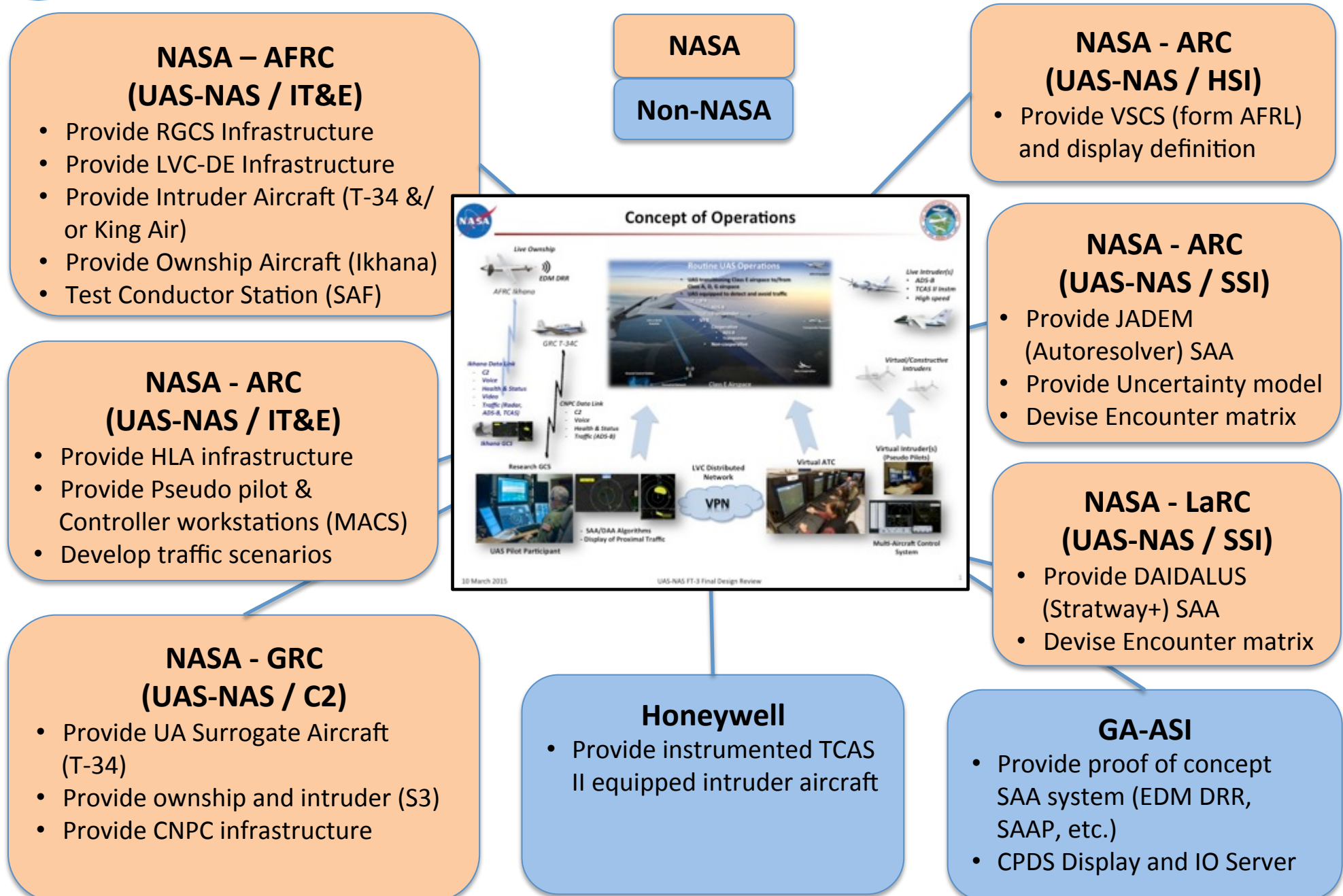


Detect-and-Avoid Overview





Integration Roles & Responsibilities Summary





Flight Test 3 Scripted Encounters

Research Objectives

- **Research Objectives**
 - **Validate CPA prediction accuracy in realistic flight conditions**
 - **Evaluate TCAS/Self-separation interoperability**
 - ownship CA/SS interaction
 - compatibility with Intruder's TCAS
 - **Validate Self-separation trajectory model for ownship maneuvers**
 - **Qualitatively evaluate pilot impression of Self-separation advisories**
 - **Validate data fusion/best source selection model**
 - **Validate sensor and tracking models used for preliminary MOPS**
 - **Evaluate TCAS II installed performance on a UAS**
 - **Inform final MOPS**



Flight Test 3 Scripted Encounters

Test Requirements

- **Test Requirements**

- **Live Ownship (OS)**

- **Low Speed OS – DRR, ADS-B, and TCAS Sensors, Sensor Fusion**

- » **Higher Priority Test Points**

- » **Ikhana**

- **EDM DRR ($\pm 110^\circ$ az and $\pm 15^\circ$ elev) non-coop sensor**
 - **ADS-B coop sensor**
 - **TCAS II v7.1 coop sensor**
 - **HON STM (sensor fusion/tracker)**

- **High Speed OS – ADS-B coop sensor**

- » **Lower Priority Test Points**

- » **250 KGS capable**

- » **CNPC equipped**

- » **S-3B-equipped with ADS-B only**

- **Onboard pilot will maneuver based on onboard display cues of commands uplinked from RGCS pilot via CNPC link**

- **Live Intruder(s)**

- **ADS-B equipped**

- **TCAS II Instrumentation for interoperability test**

- **High speed (250 KGS capable)**

- **Multiple – 2**



Config #1a



Config #1b



Test Configuration #1a: Scripted Encounters (Ikhana)

Live Ownership



Ikhana Data Link

- C2
- Voice
- Health & Status
- Video
- Traffic (Radar, ADS-B, TCAS)

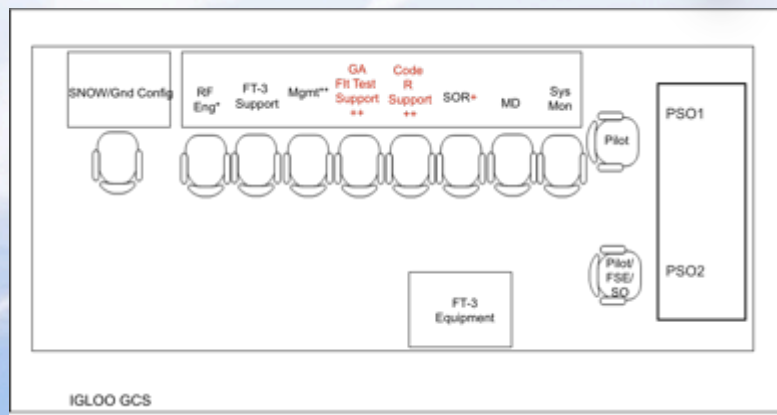


ADS-B Out

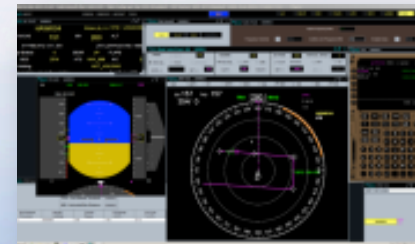
Live Intruder(s)

- ADS-B
- TCAS II
- High speed

*Displays of Proximal Traffic
SAA/DAA Algorithms*



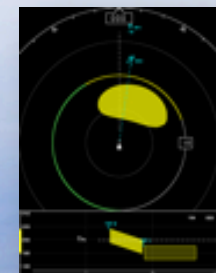
Ikhana GCS



Stratway+/DAIDALUS



Autoresolver



CPDS



Flight Test 3 Scripted Encounters

Test Requirements

- **Test Requirements**

- **Live Ownship (OS)**

- Low Speed OS – DRR, ADS-B, and TCAS Sensors, Sensor Fusion

- » **Higher Priority Test Points**

- » **Ikhana**

- EDM DRR ($\pm 110^\circ$ az and $\pm 15^\circ$ elev) non-coop sensor
 - ADS-B coop sensor
 - TCAS II v7.1 coop sensor
 - HON STM (sensor fusion/tracker)

Config #1a

- **High Speed OS – ADS-B coop sensor**

- » **Lower Priority Test Points**

- » **250 KGS capable**

- » **CNPC equipped**

- » **S-3B-equipped with ADS-B only**

- **Onboard pilot will maneuver based on onboard display cues of commands uplinked from RGCS pilot via CNPC link**

Config #1b

- **Live Intruder(s)**

- ADS-B equipped
 - TCAS II Instrumentation for interoperability test
 - High speed (250 KGS capable)
 - Multiple – 2





Test Configuration #1b: Scripted Encounters (S-3B)

Live Ownship



GRC S-3B

CNPC Data Link

- C2
- Voice
- H&S
- Traffic



ADS-B Out

Live Intruders

- ADS-B
- TCAS II
- High speed

Displays of Proximal Traffic SAA/DAA Algorithms





Research GCS

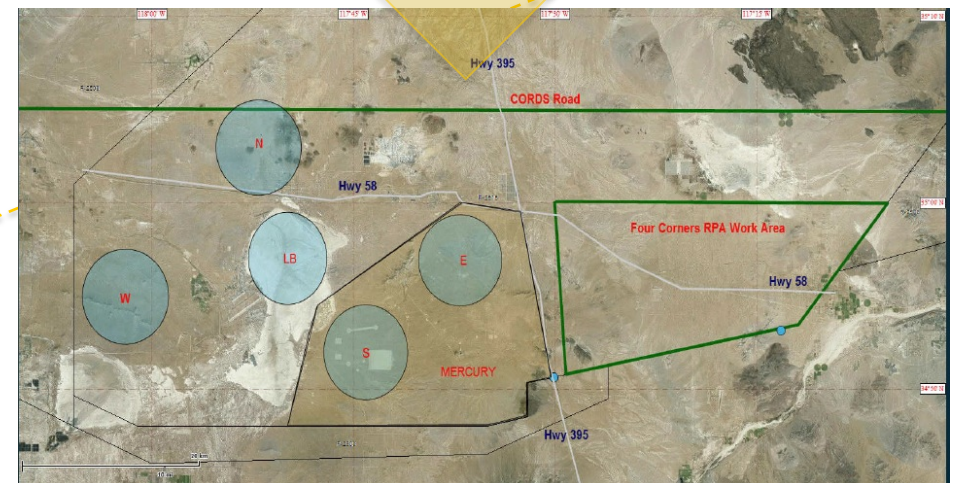
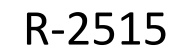
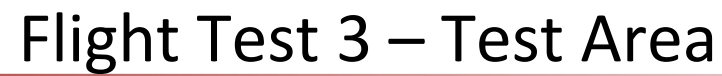


Autoresolver



FT-3 Aircraft Equipment Requirements

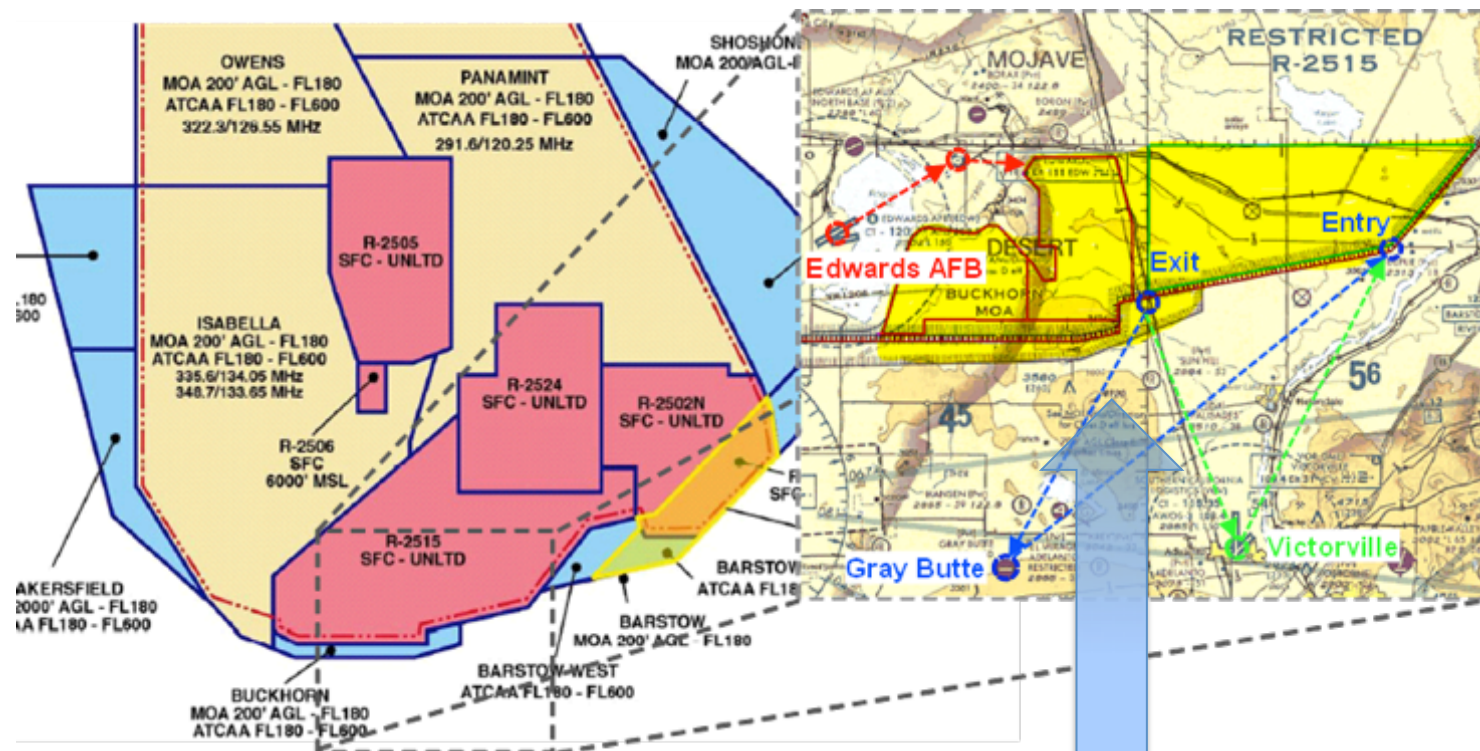
Aircraft	Responsibility	EDM DRR	ADS-B	GPS	TCAS-II	Config 1A	Config 1B	Config 2
	Ownship NASA AFRC's Ikhana UAS	✓	✓	✓	✓	✓		
	Ownship or Intruder UAS Surrogate NASA GRC, T-34 Mentor		✓	✓				✓
	NASA GRC S-3B Viking High Speed Ownship or Intruder		✓	✓		✓	✓	
	Honeywell Beechcraft King Air C90 manned aircraft used as an intruder		✓	✓	✓	✓	✓	✓
	Second / Backup Intruder NASA AFRC T-34		✓	✓		✓	✓	✓
	Second / Backup Intruder NASA AFRC King Air		✓	✓		✓	✓	✓



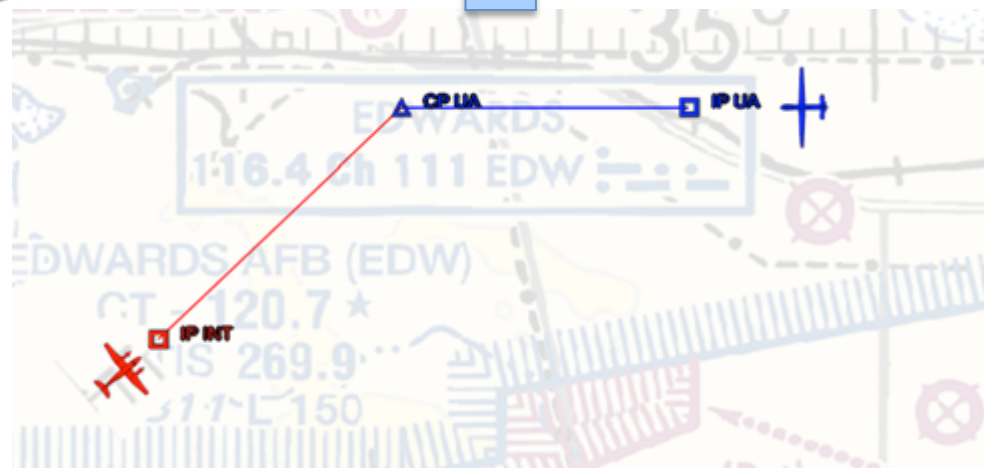
Mercury Spin & Four Corners



Configuration 1 Encounter Airspace



- Pairwise, low speed-low speed encounters that requires Ikhana ownship versus a low speed intruder aircraft (C90 or T-34C) [Configuration 1A];
- Pairwise, low speed-high speed encounters that requires Ikhana ownship versus S-3B [Configuration 1A];
- Pairwise, low speed-low/high speed encounters that requires Ikhana ownship versus multi-intruder aircraft (one low speed intruder (T-34C or C90) and one high speed intruder (S-3B) [Configuration 1A];
- Pairwise, high speed-low speed encounters that requires S-3B ownship versus a low speed intruder (T-34C or C90) [Configuration 1B].





FT3 Sortie flow

JADEM			CPDS		Stratway+			High Speed		
1	2	3	4	5	6	7	8	9	10	11
17-Jun	18-Jun	22-Jun	24-Jun	26-Jun	7-Jul	9-Jul	10-Jul	20-Jul	22-Jul	24-Jul
W	Th	M	W	F	Tu	Th	F	M	W	F
18 - L12A	10 - L13A	15 - L15A	137 - L53C	124 - L55G (90)	1 - L42A	3 - L55A	62 - L12N	79 - H12A	80 - H12A	83 - H12A
19 - L52A	32 - L13C	37 - L15C	137 - L53C	108 - L12A (2)	2 - L42B	4 - L55B	63 - L12N	81 - H12A	82 - H12A	85 - H12A
20 - L32A	52 - L13D	57 - L15D	146 - L54D	107 - L12A (1)	21 - L42C	22 - L55C	8 - M59Q	87 - H12C	88 - H12C	91 - H12C
29 - L12C	16 - L16A	11 - L13A	146 - L54D	112 - L11A (2)	42 - L42D	43 - L55D	9 - M59U	89 - H12C	90 - H12C	93 - H12C
30 - L52C	38 - L16C	33 - L13C	140 - L55A	111 - L11A (1)	64 - L42F	65 - L55F	27 - M59R	95 - H12D	96 - H12D	99 - H12D
31 - L32C	58 - L16D	53 - L13D	140 - L55A	164 - L42M	25 - L53C	7 - L57A	28 - M59V	97 - H12D	98 - H12D	101 - H12D
49 - L12D	14 - L15A	17 - L16A	151 - L56F	165 - L52M (1)	46 - L53D	24 - L57C	48 - M59S	72 - H42A	80 - H12A	84 - H12A
50 - L52D	36 - L15C	39 - L16C	151 - L56F	166 - L52M (2)	68 - L53F	45 - L57D	70 - M59T	73 - H42C	82 - H12A	86 - H12A
51 - L32D	56 - L15D	59 - L16D	159 - L57D	167 - L52M (3)	26 - L54C	67 - L57F	71 - M59W	74 - H42D	88 - H12C	92 - H12C
60 - L12E	15 - L15A	18 - L12A	159 - L57D	168 - L52M (4)	47 - L54D	21 - L42C	8 - M59Q	75 - H42F	90 - H12C	94 - H12C
40 - L12M	37 - L15C	19 - L52A	128 - L32A	169 - M79X (1)	69 - L54F	42 - L42D	9 - M59U	76 - M59R	96 - H12D	100 - H12D
62 - L12N	57 - L15D	20 - L32A	128 - L32A	170 - M79X (2)	5 - L56A	64 - L42F	27 - M59R	77 - M59S	98 - H12D	102 - H12D
12 - L14A	11 - L13A	29 - L12C	129 - L32C	171 - M79X (3)	6 - L56B	25 - L53C	28 - M59V	78 - M59T	79 - H12A	103 - H12H
34 - L14C	33 - L13C	30 - L52C	129 - L32C	160 - M67Q	23 - L56C	46 - L53D	48 - M59S	76 - M59R	81 - H12A	105 - H12H
54 - L14D	53 - L13D	31 - L32C	130 - L32D	162 - M27Q	44 - L56D	26 - L54C	70 - M59T	77 - M59S	87 - H12C	Margin
61 - L12E	17 - L16A	49 - L12D	130 - L32D	172 - M27Q	66 - L56F	47 - L54D	71 - M59W	78 - M59T	89 - H12C	
41 - L12M	39 - L16C	50 - L52D	131 - L32F	161 - M68Q	20 - L32A	22 - L55C	31 - L32C	72 - H42A	95 - H12D	
63 - L12N	59 - L16D	51 - L32D	131 - L32F	163 - M28Q	31 - L32C	43 - L55D	51 - L32D	73 - H42C	97 - H12D	
13 - L14A	9 - M59U	12 - L14A	152 - L32B	173 - M28Q	51 - L32D	65 - L55F	62 - L12N	74 - H42D	136 - L53A	
35 - L14C	48 - M59S	34 - L14C	152 - L32B	132 - L31A	68 - L53F	24 - L57C	63 - L12N	75 - H42F	136 - L53A	
55 - L14D	71 - M59W	54 - L14D	153 - L32G	132 - L31A	69 - L54F	45 - L57D	133 - L31C	110 - L12A (4)	138 - L53D	
61 - L12E	60 - L12E	10 - L13A	153 - L32G	155 - L31B	23 - L56C	67 - L57F	133 - L31C	109 - L12A (3)	138 - L53D	
41 - L12M	40 - L12M	32 - L13C	154 - L32H	155 - L31B	44 - L56D	158 - L57A	134 - L31D	114 - L11A (4)	139 - L53F	
63 - L12N	62 - L12N	52 - L13D	154 - L32H	156 - L31G	66 - L56F	158 - L57A	134 - L31D	113 - L11A (3)	139 - L53F	
13 - L14A	14 - L15A	16 - L16A	115 - L32G (110)	156 - L31G	122 - L31G (90)	119 - L54G (110)	135 - L31F	127 - L92P	141 - L55C	Sortie length concerns
35 - L14C	36 - L15C	38 - L16C	117 - L53G (110)	157 - L31H	125 - L51G (90)	118 - L55G (110)	135 - L31F	123 - L53G (90)	141 - L55C	
55 - L14D	56 - L15D	58 - L16D	121 - L32G (90)	157 - L31H	116 - L51G (110)	120 - L56G (110)		126 - L56G (90)		

Total Sorties – 11
Total Encounters – 282

- 105 JADEM
- 80 Stratway+
- 83 CPDS
- 14 - Config 1b JADEM

Priority 1
Priority 2
Priority 3
Priority 4

JADEM Only:

Autoresolver 1

Autoresolver 2

XML File Change

Display Change:

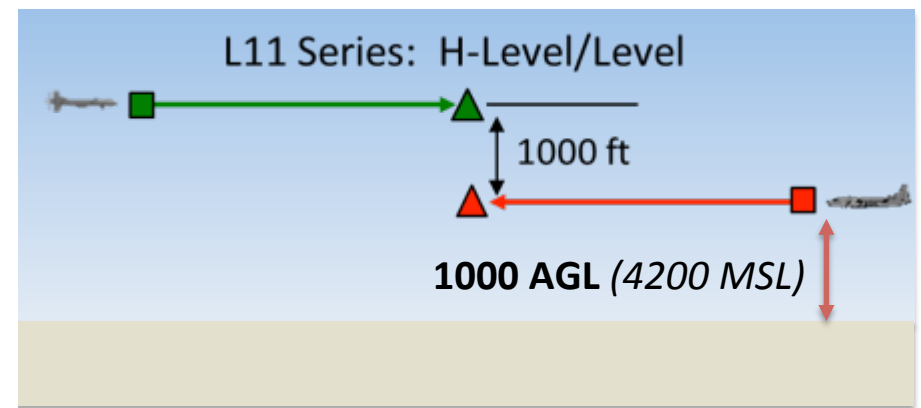
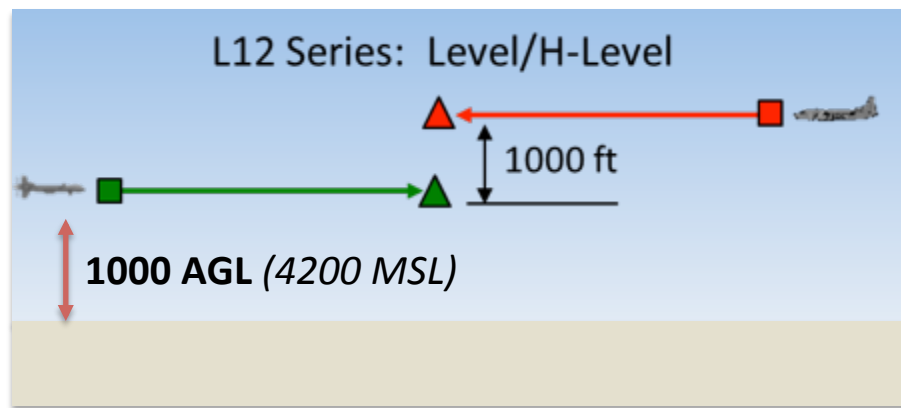
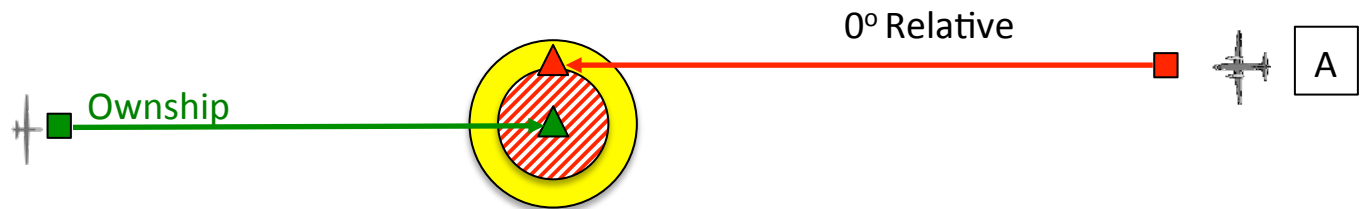
CPDS

Stratway+



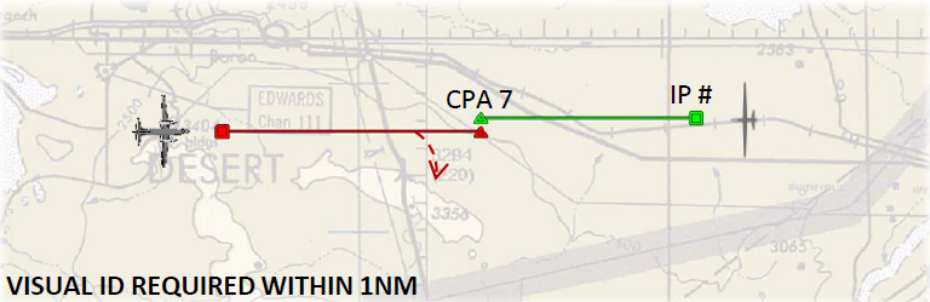
GA-ASI Radar Encounters (Ground Clutter)

Flight 5 26-Jun	Flight 9 20-Jul
108 - L12A (2)	110 - L12A (4)
107 - L12A (1)	109 - L12A (3)
112 - L11A (2)	114 - L11A (4)
111 - L11A (1)	113 - L11A (3)



- Initial Point (IP)
- Maneuver Point (MP)
- ▲ Closest Point of Approach (CPA)
- ⊘ Lateral Offset = 0.5 nmi
- SS Alerting Boundary=0.75 nmi
- Minimum Altitude Offset ≥ 1000 ft

FT-3, Configuration 1a		Aircraft: NASA 870		S/N:148		Version 6	
Card#		L56A				Ownship	



VISUAL ID REQUIRED WITHIN 1NM

1. TC announces COMEX time.
2. Announce "<Callsign>, IP Inbound, altitude & special procedure review" crossing IP.
3. Aircraft on condition at least 2 minutes prior to CPA.
4. TC calls "terminate" when run complete.
5. TC announces next Card Number.

LOST LINK MISSION:
 LL-CP7 (WP7)

<input type="checkbox"/> AR 1	<input type="checkbox"/> AR 2	<input type="checkbox"/> Stratway+	<input type="checkbox"/> CPDS
<input type="checkbox"/> OFF	<input type="checkbox"/> Advisory	<input type="checkbox"/> AUTO	
<input type="checkbox"/> ADS-B	<input type="checkbox"/> RADAR	<input type="checkbox"/> TCAS	<input type="checkbox"/> TRACKER

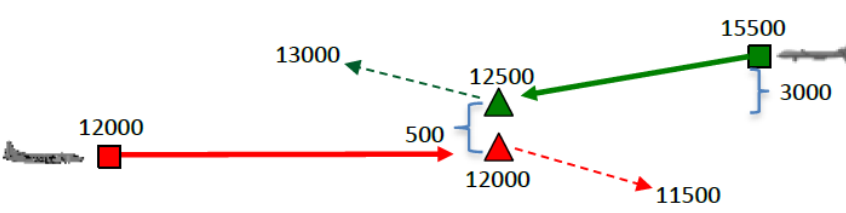
DECONFLICTION ALT:
 13000

<input type="checkbox"/> AR 1	<input type="checkbox"/> AR 2	<input type="checkbox"/> Stratway+	<input type="checkbox"/> CPDS
<input type="checkbox"/> OFF	<input type="checkbox"/> Advisory	<input type="checkbox"/> AUTO	
<input type="checkbox"/> ADS-B	<input type="checkbox"/> RADAR	<input type="checkbox"/> TCAS	<input type="checkbox"/> TRACKER

ABORT PROCEDURE

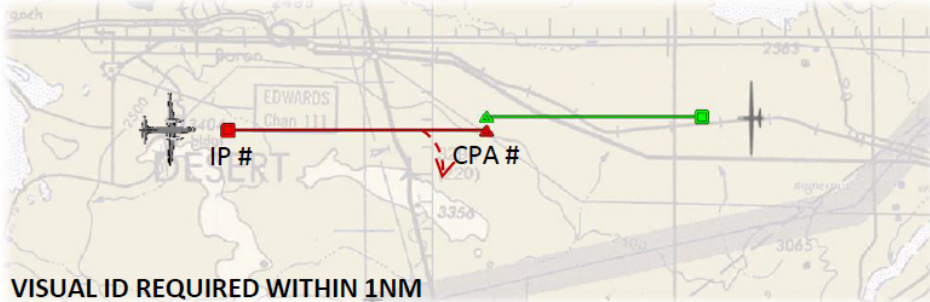
13000

MAINTAIN HDG



COMEX TIME:			IP TIME ADJUST:			
PT	LATITUDE	LONGITUDE	ALT V/V	DIST MC	G/S	TIME HACK
IP	N34° 57.09'	W117° 18.47'	15500	7.5	150	
	N34° 57' 05.4"	W117° 18' 28.2"	-1000	258		
CPA7	N34° 57.09'	W117° 27.62'	12500	0.0	150	
	N34° 57' 05.4"	W117° 27' 37.2"	0	258		

FT-3, Configuration 1a		Aircraft: N3GC		S/N:148		Version 6	
Card#		L56A				Intruder 1	



VISUAL ID REQUIRED WITHIN 1NM

1. TC announces COMEX time.
2. Announce "<Callsign>, IP Inbound, altitude & special procedure review" crossing IP.
3. Aircraft on condition at least 2 minutes prior to CPA.
4. TC calls "terminate" when run complete.
5. TC announces next Card Number.

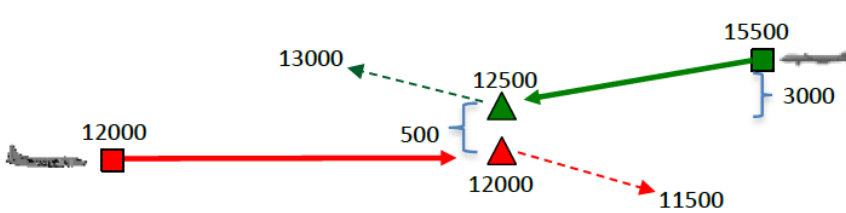
DECONFLICTION ALT:
 12000

<input type="checkbox"/> AR 1	<input type="checkbox"/> AR 2	<input type="checkbox"/> Stratway+	<input type="checkbox"/> CPDS
<input type="checkbox"/> OFF	<input type="checkbox"/> Advisory	<input type="checkbox"/> AUTO	
<input type="checkbox"/> ADS-B	<input type="checkbox"/> RADAR	<input type="checkbox"/> TCAS	<input type="checkbox"/> TRACKER

ABORT PROCEDURE

11500

120



COMEX TIME:			IP TIME ADJUST:			
PT	LATITUDE	LONGITUDE	ALT V/V	DIST MC	G/S	TIME HACK
IP	N34° 56.60'	W117° 38.60'	12000	9.0	180	
	N34° 56' 35.8"	W117° 38' 36.0"	0	78		
CPA	N34° 56.60'	W117° 27.62'	12000	0.0	180	
	N34° 56' 35.8"	W117° 27' 37.2"	0	78		



Ikhana FT-3 Config 1a Typical Mission Flow

- T-1 (Noon-ish): Day before detailed brief
 - To protect crew rest for back-to-back flights
- T-0 (0415): All crew pre-flight delta brief
- (0430): Individual aircraft crew brief, as required
- Each aircraft take-off to arrive within R2515 at required time
 - 0600 for Ikhana
- Ikhana and single manned aircraft perform altitude calibration
 - If multiple intruders, manned and manned aircraft perform altitude calibration
- Prior to each scenario
 - Verify scenario number
 - Verify LL Mission and Initial Way Point and Altitude Loaded (Ikhana)
 - Verify FT-3 software mode (Ikhana)
 - Verify expected FT-3/Ikhana behavior
 - Review scenario abort procedures
 - Verify Nav error
 - Verify appropriate display is being displayed to pilots (Ikhana)



SAF UAS-NAS TC/TD Workstation

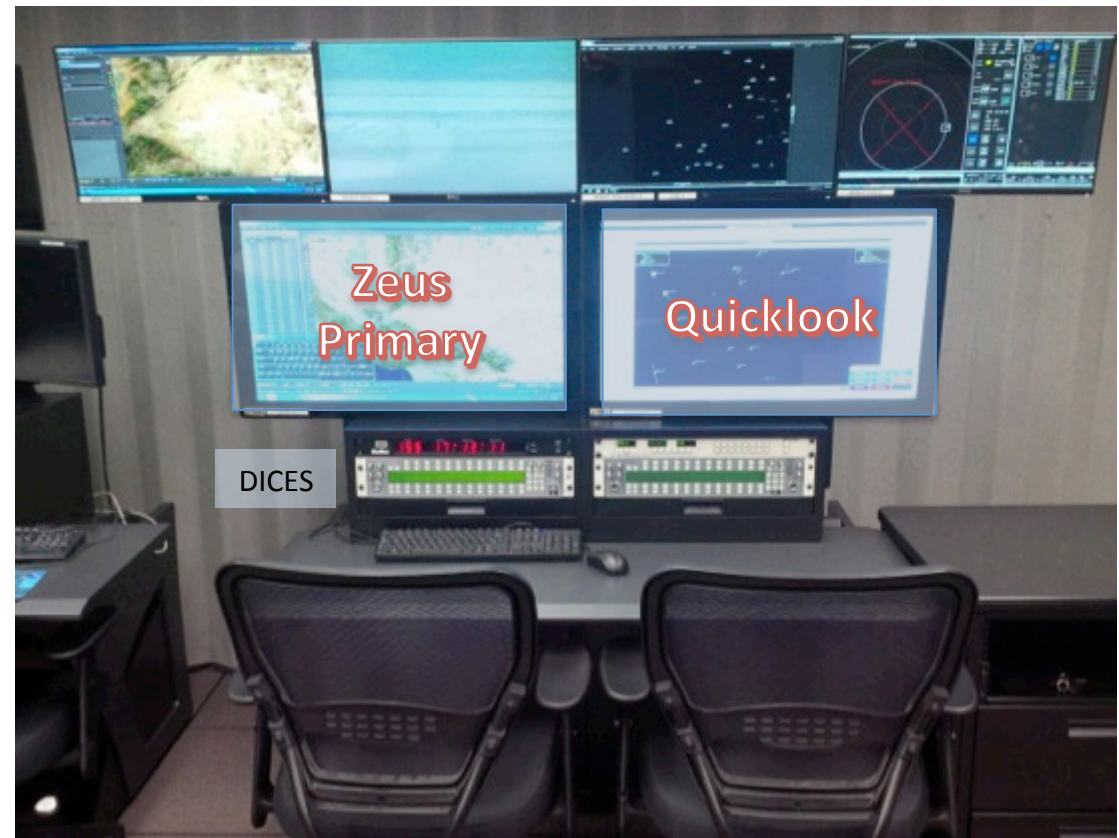
- Provides 'full picture' to Test Conductor & Test Director
- Enhancements include:
 - Large screen displays (32")
 - SS display repeater
 - Common architecture

Zeus
Secondary

Ikhana
Nose Video

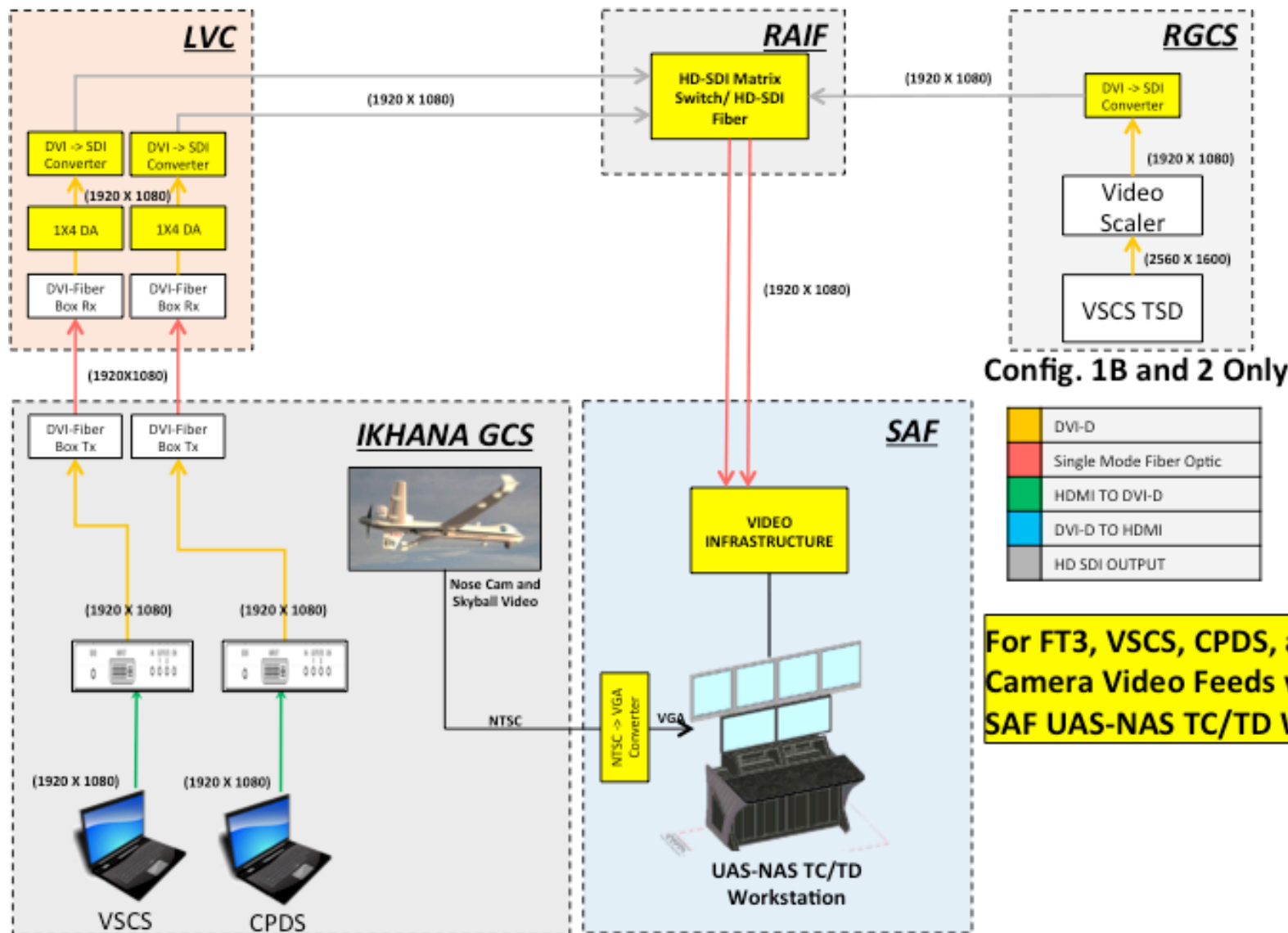
Ikhana MTS
Video

SS Display
Repeater



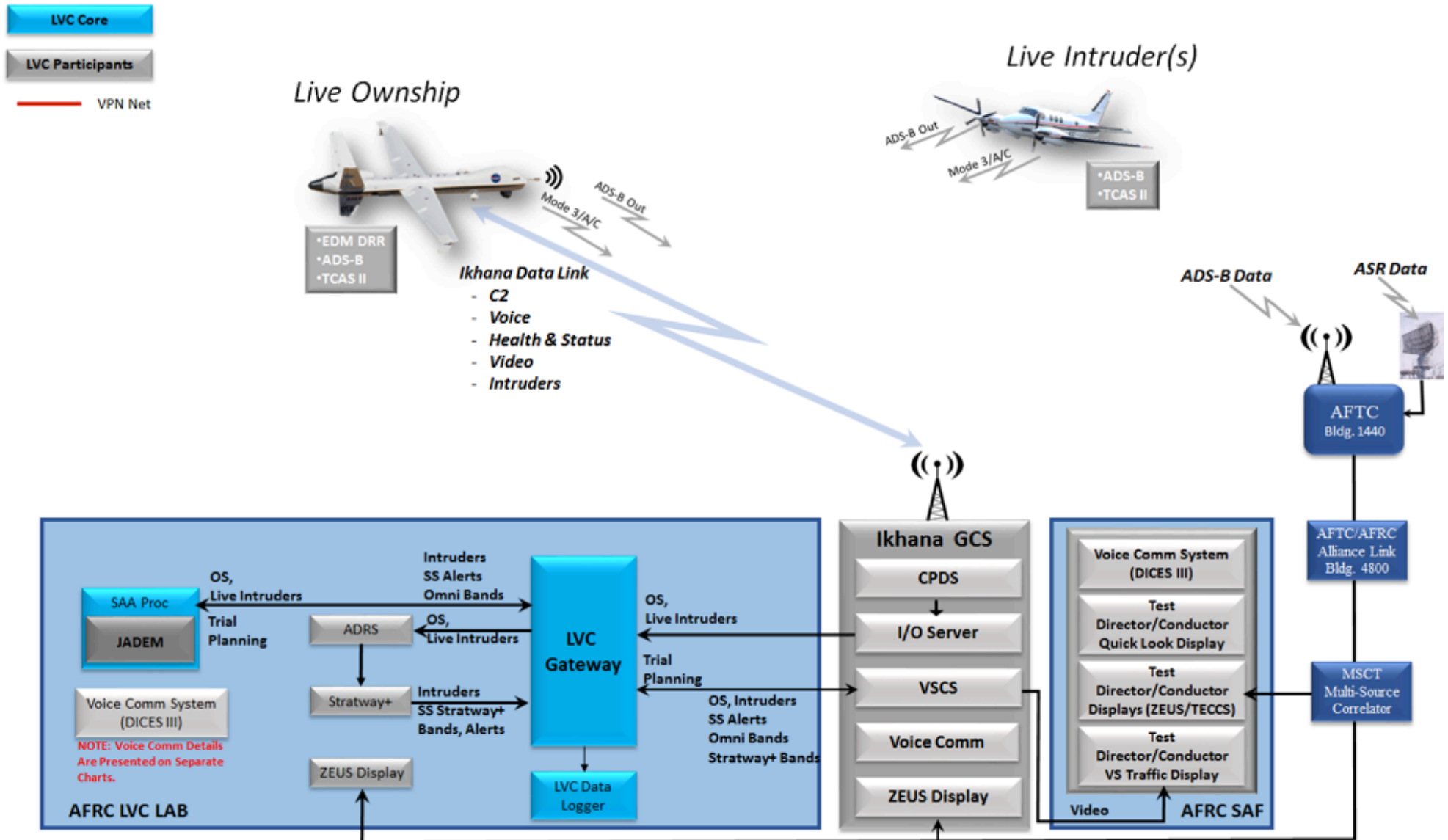


Video Distribution System



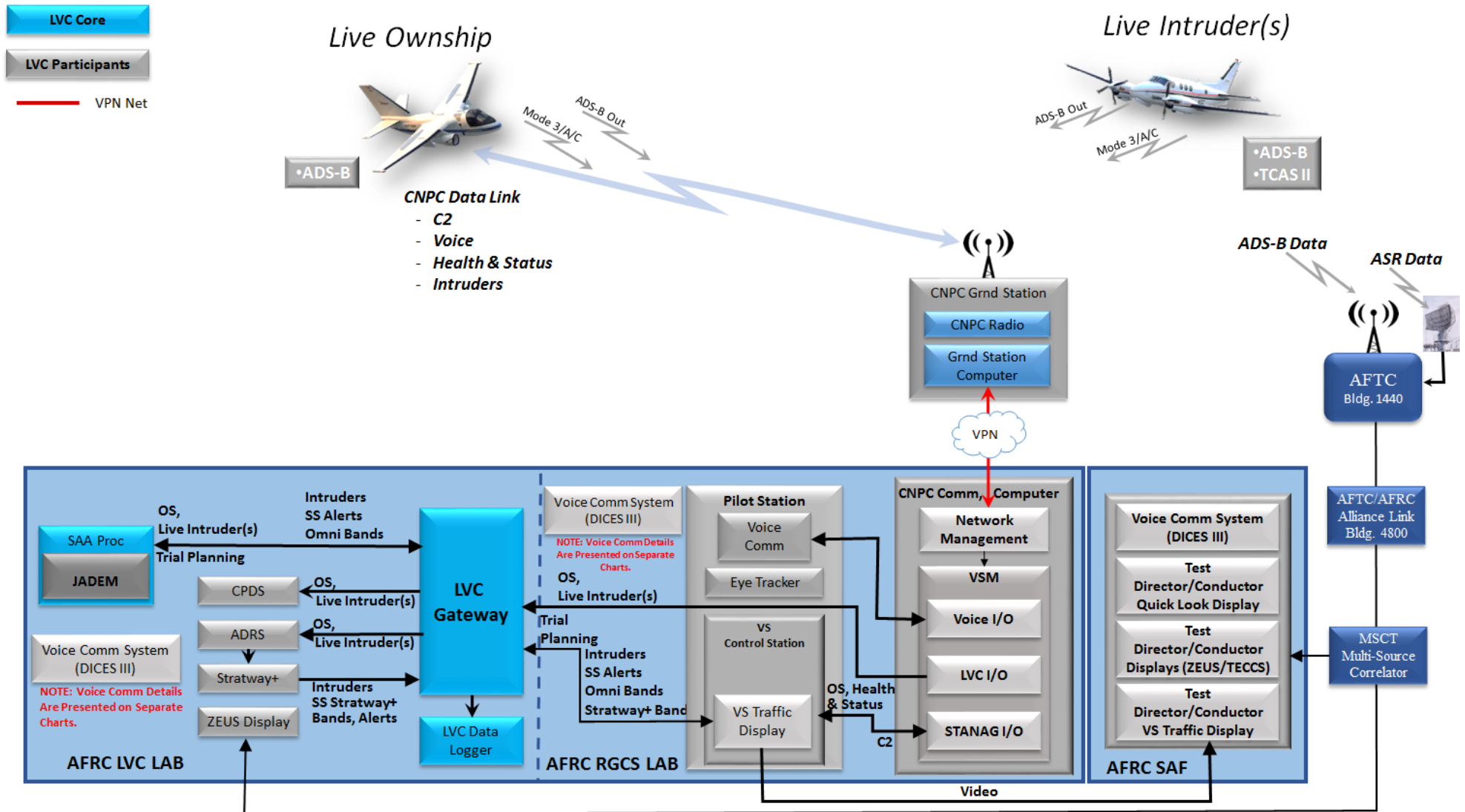


FT3: Configuration 1A (Scripted-Low Speed Ownship) – Ikhana





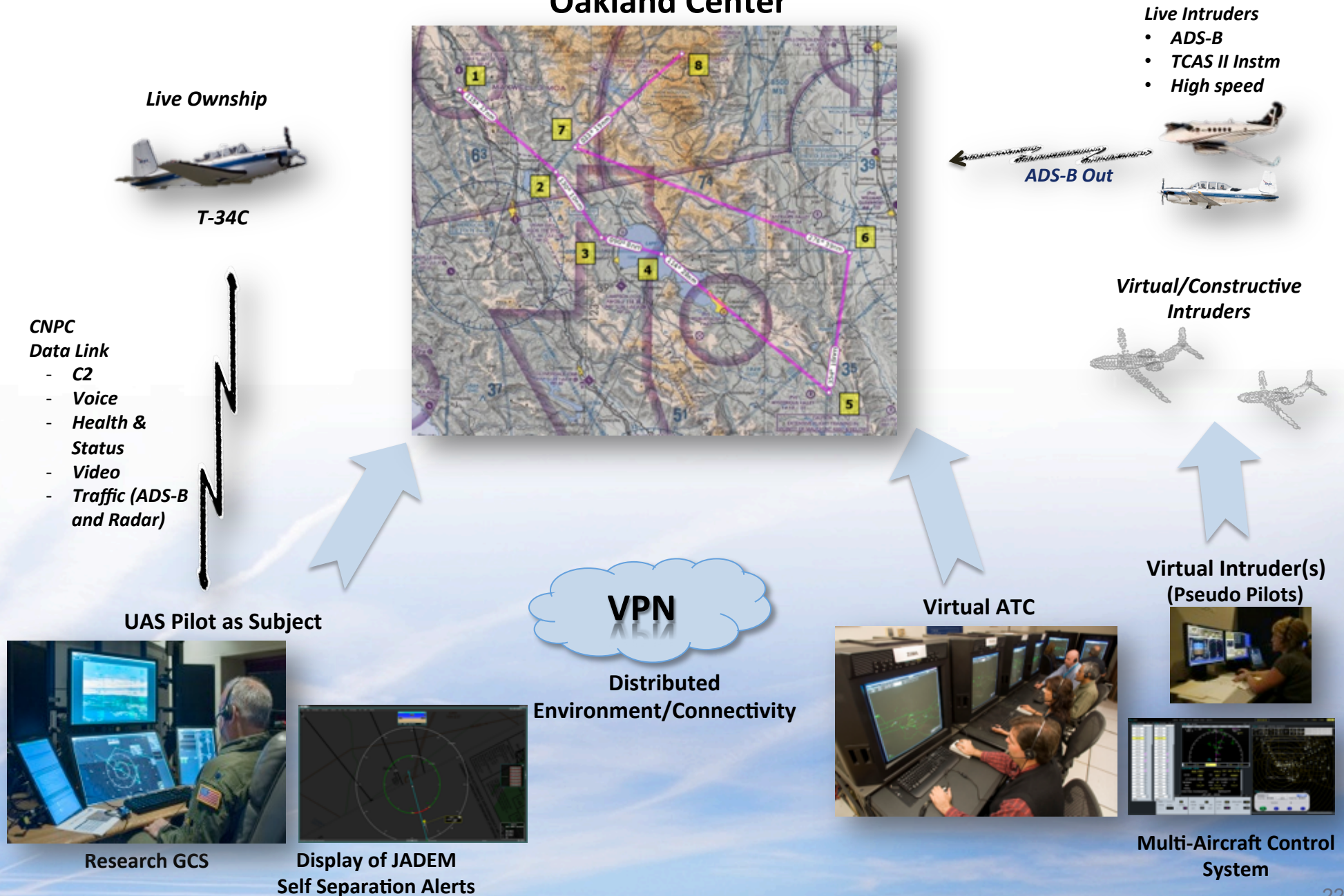
FT3: Configuration 1B (Pairwise-High Speed Ownership) – S-3B





Test Configuration #2: Full Mission

Oakland Center





Flight Test 3 Full Mission Scenario Evaluations

Research Objectives

- **Research Objectives**
 - Evaluate the integrated Self Separation algorithms, GCS Traffic displays, and prototype CNPC systems in a realistic environment
 - Evaluate UAS pilots' ability to maintain well clear
 - Gather objective and subjective pilot data to evaluate/validate Well-clear definition
 - Analyze the performance of 4th generation CNPC systems



Flight Test 3 Full Mission Scenario Evaluations

Test Requirements







- **Test Requirements**

- **Fire Line Route at 12k-15k MSL**
- **Six encounters require maneuvering to prevent WCV; four with live intruders**
- **Live Ownship**
 - T-34C UAS Surrogate controlled from the RGCS
 - » CNPC equipped
 - » ADS-B coop sensor
 - » Lateral maneuvering (autopilot) via heading commands uplinked from the RGCS pilot
 - » Vertical maneuvering via display cues of altitude commands uplinked from RGCS pilot
- **Coop Live Intruder(s)**
 - ADS-B equipped
 - Multiple – 2
- **Non-Coop Intruders will be simulated using DRR Rng, Az, and Elev models/filters in JADEM**





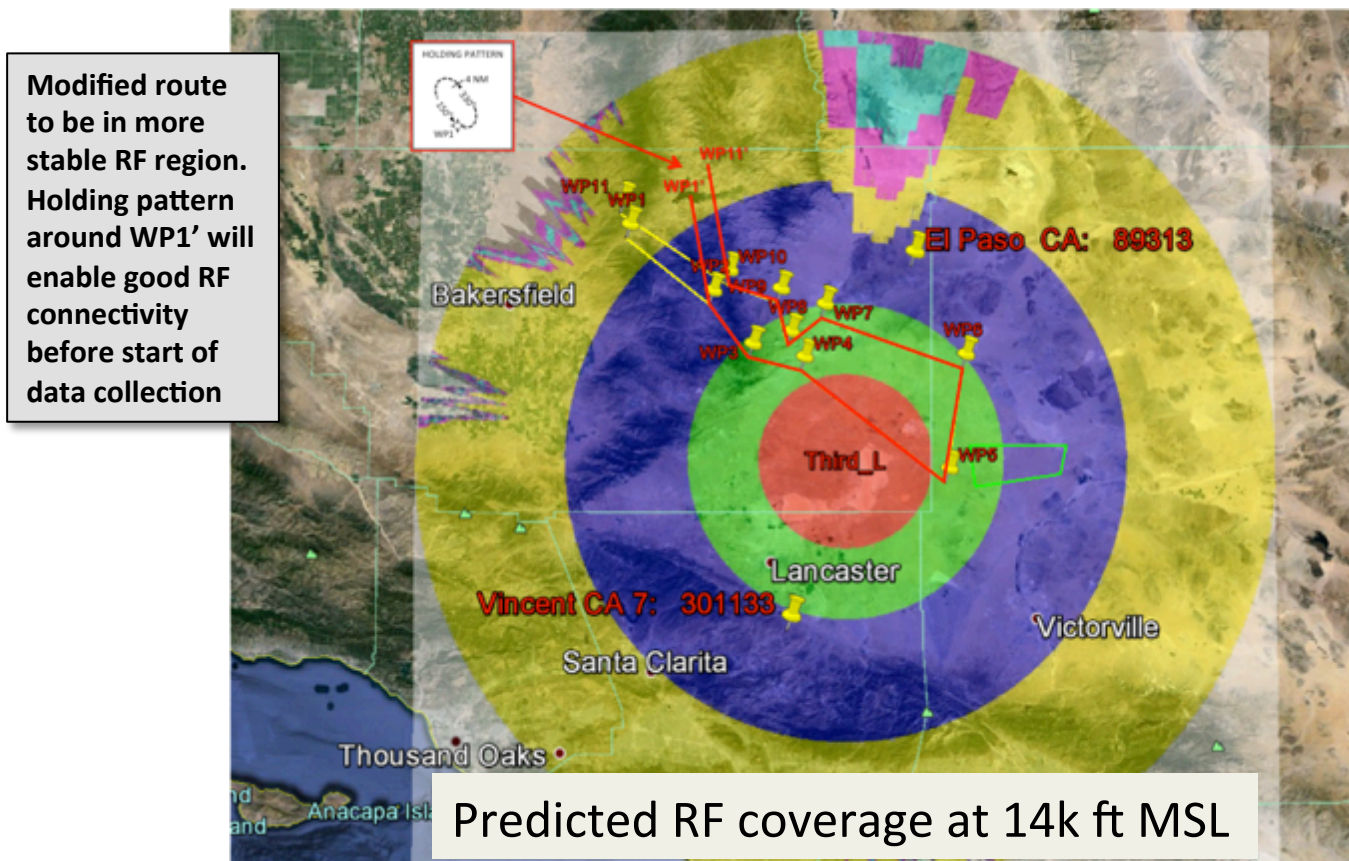
FT-3 Aircraft Equipment Requirements

Aircraft	Responsibility	EDM DRR	ADS-B	GPS	TCAS-II	Config 1A	Config 1B	Config 2
	Ownship NASA AFRC's Ikhana UAS	✓	✓	✓	✓	✓		
	Ownship or Intruder UAS Surrogate NASA GRC, T-34 Mentor		✓	✓				✓
	NASA GRC S-3B Viking High Speed Ownship or Intruder		✓	✓		✓	✓	
	Honeywell Beechcraft King Air C90 manned aircraft used as an intruder		✓	✓	✓	✓	✓	✓
	Second / Backup Intruder NASA AFRC T-34		✓	✓		✓	✓	✓
	Second / Backup Intruder NASA AFRC King Air		✓	✓		✓	✓	✓



CNPC Ground Stations

- CNPC ground station scheduled for installation the week of 7/6/15.
- Flight testing of RF coverage from the ground station is currently scheduled for 7/14/15



- To stand up a tower at ATF2.



Full Mission Flight Airspace



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- Full Mission flown entirely within R-2508 Complex
- Airspace includes: R-2515 + Porterville, Bakersfield & Isabella MOAs
- Altitudes 12-15K ft MSL
- 40 min mission (T-34C ownship aircraft)
- 2-live intruders (King Air & T-34) performing 2 runs each
- 5-virtual intruders performing 1 run each



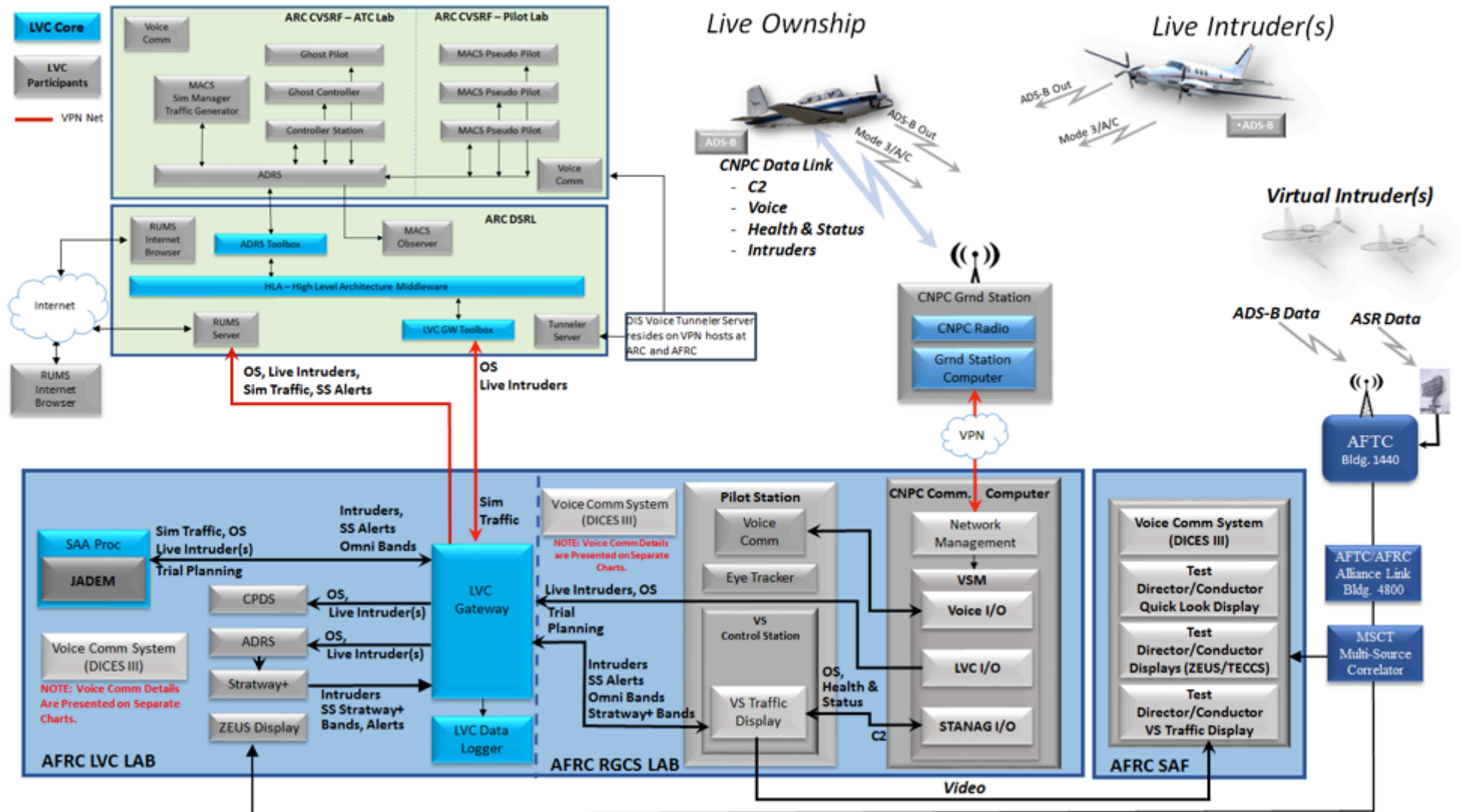
RGCS Stations



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FT3: Configuration 2 (Full Mission Scenario) – Surrogate UA







Backup



Self-Sep Algorithms Under Test for FT3

- 3 Self-Separation Algorithms under test
 - AutoResolver
 - Directive SS Algorithm developed by NASA ARC SSI Team
 - Results displayed on Vigilant Spirit Control Station (VSCS) display
 - Stratway +
 - Passive SS Algorithm developed by NASA LaRC SSI Team
 - Results displayed on VSCS display
 - Conflict Prediction and Display System (CPDS)
 - Passive SS Algorithm provided by GA-ASI
 - Algorithm and Display integrated as one unit



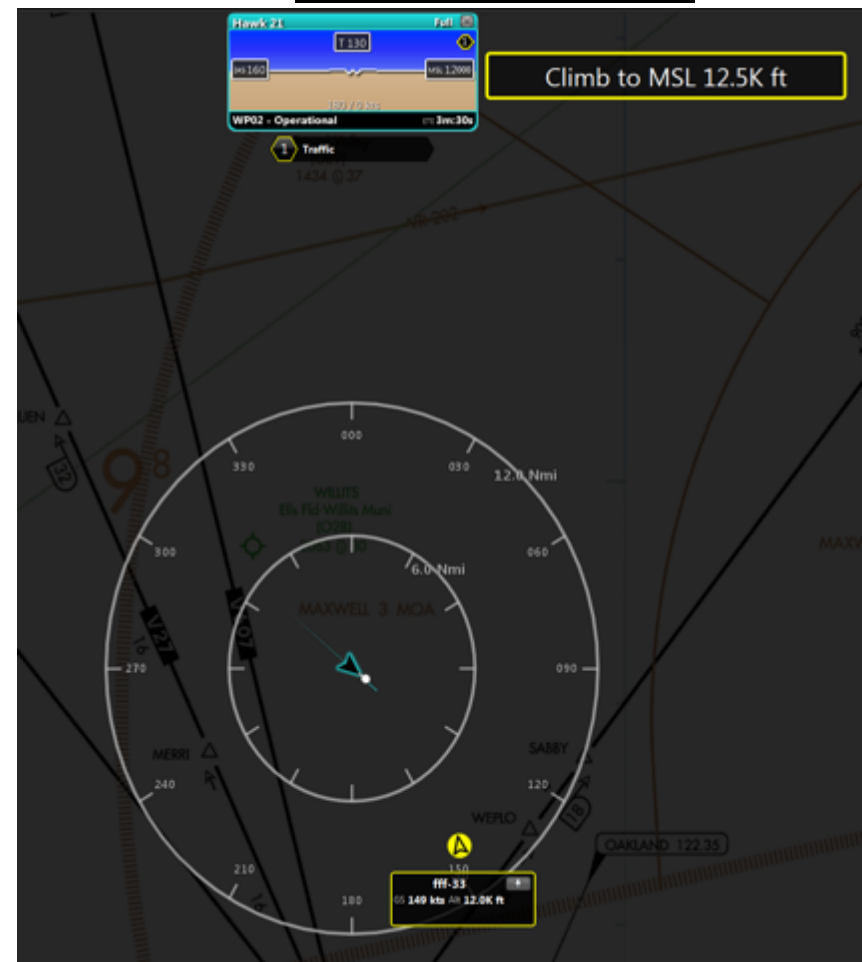
Autoresolver

- Autoresolver's recommended maneuver will appear at top center of display for **Corrective** and **Warning** alerts only

Turn Maneuver



Altitude Maneuver





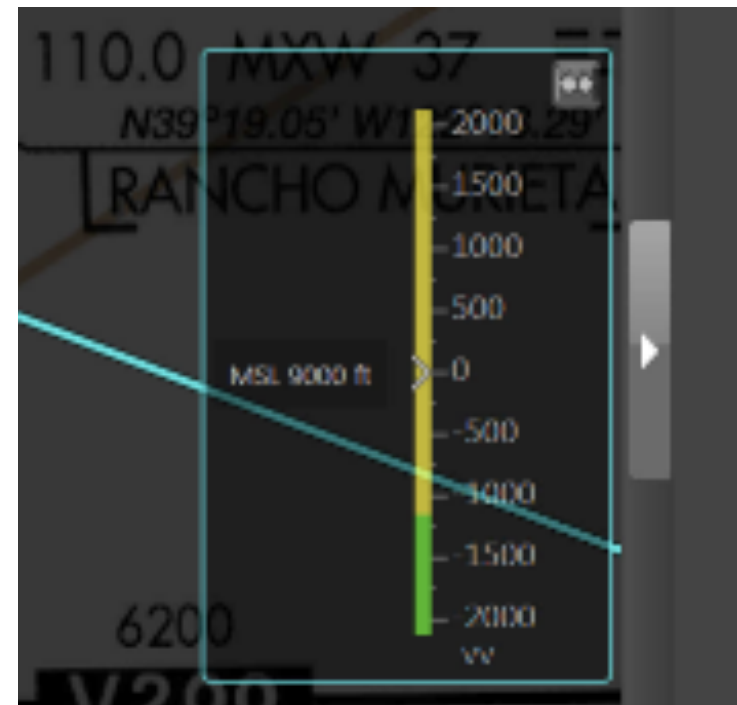
Stratway Self-Separation Bands

- Self-separation bands indicate headings and/or vertical speeds that will result in a loss of well clear.
- Both bands are updated constantly to reflect the most up-to-date information.

Heading Bands



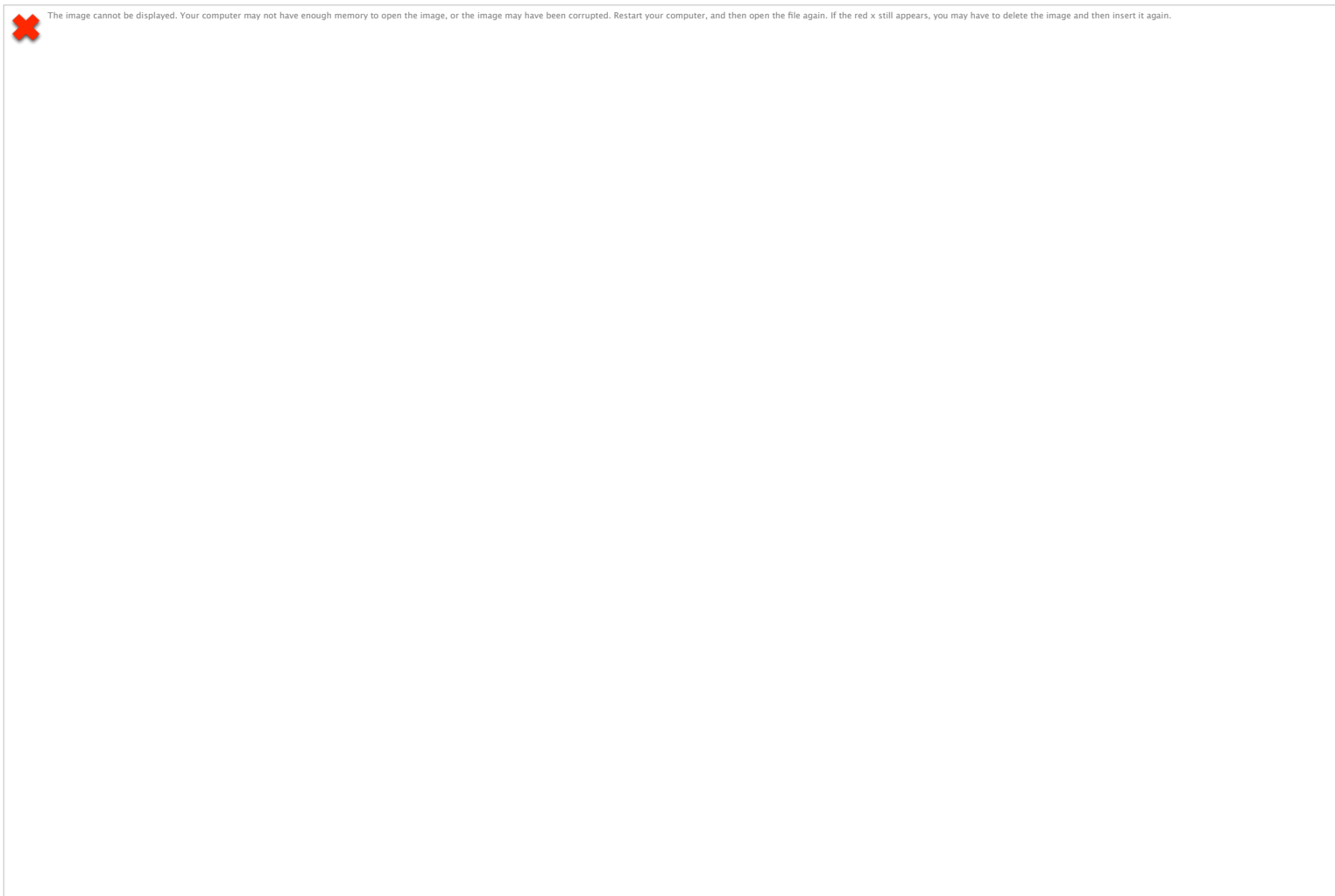
Vertical Speed Band





CPDS

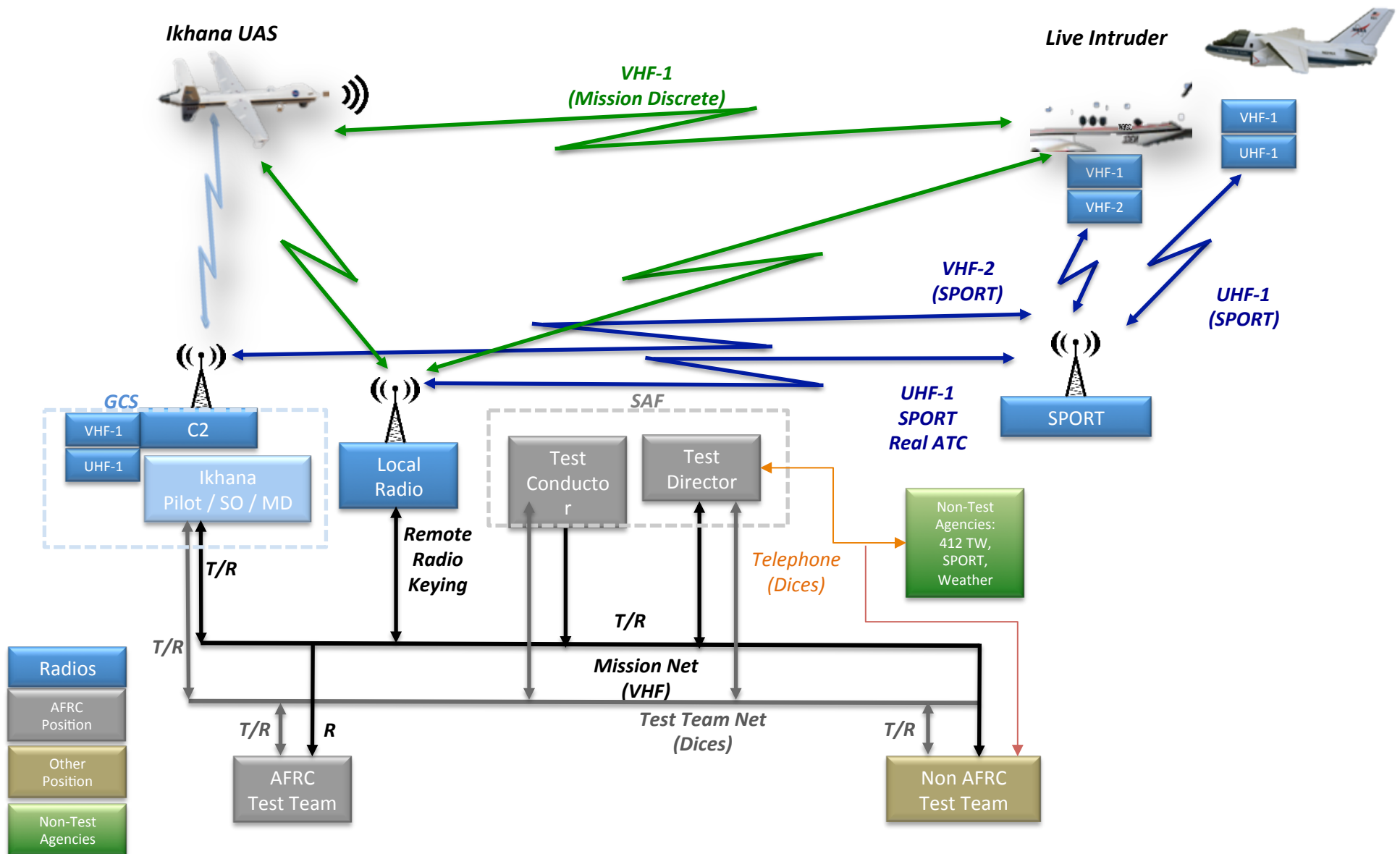
- CDTI provides the operator with a 2-D plan view of ownship and surrounding airspace traffic when present. It also provides SA of potential conflicts.





IT&E Flight Test 3 – Configuration 1A

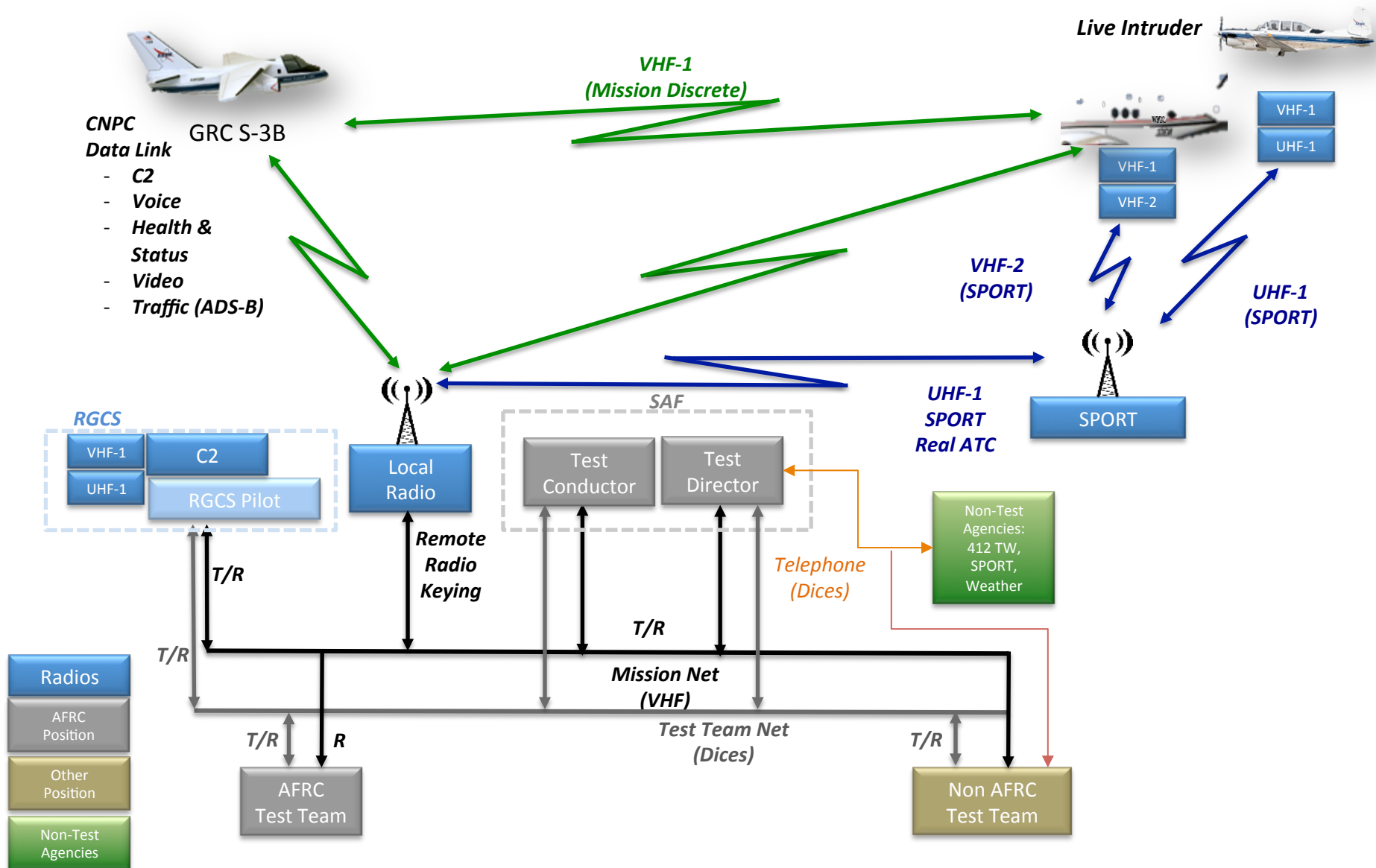
Voice Communications Architecture





Flight Test 3 – Configuration 1B

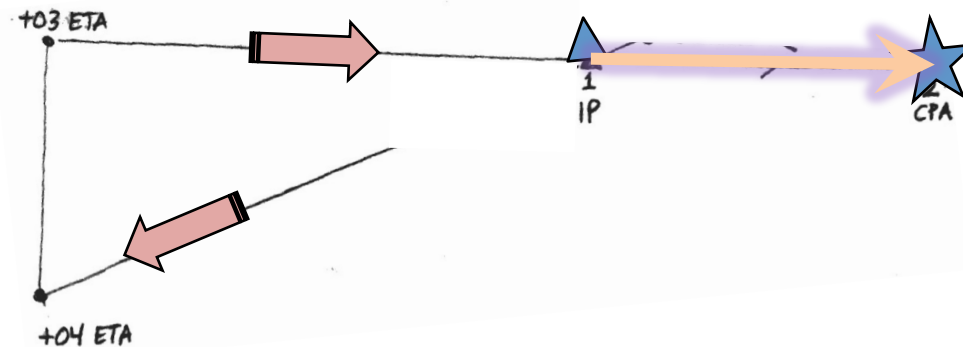
Voice Communications Architecture





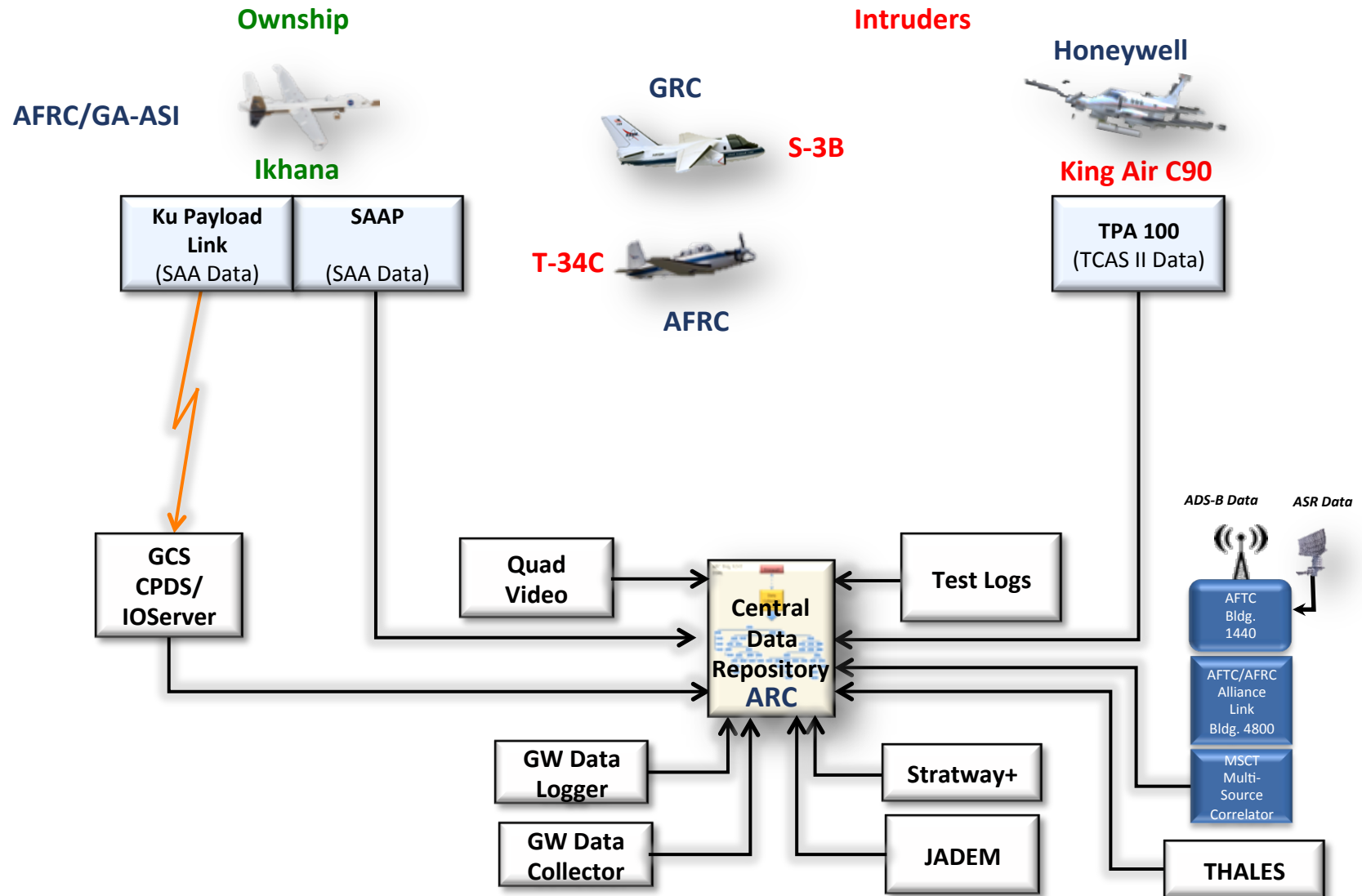
Example Ikhana Circuit / Setup Tasks (Each Run)

- Ensure can meet next IP timing (adjust pattern / speed as required)
- Downwind tasks:
 - Update Next Lost Link Start Point (far end of run line, beyond CPA),
 - Update ILLH to match run, Set Control Point on IP
 - MD give abbreviated card review
- Inbound leg to IP:
 - Final adjustments (timing / track); get ON PARAMETERS at IP
 - Keep on Track & Maintain Ground Speed to the CPA
 - At IP... Call: **IP inbound, altitude, *Special procedure is reviewed (*abort)**



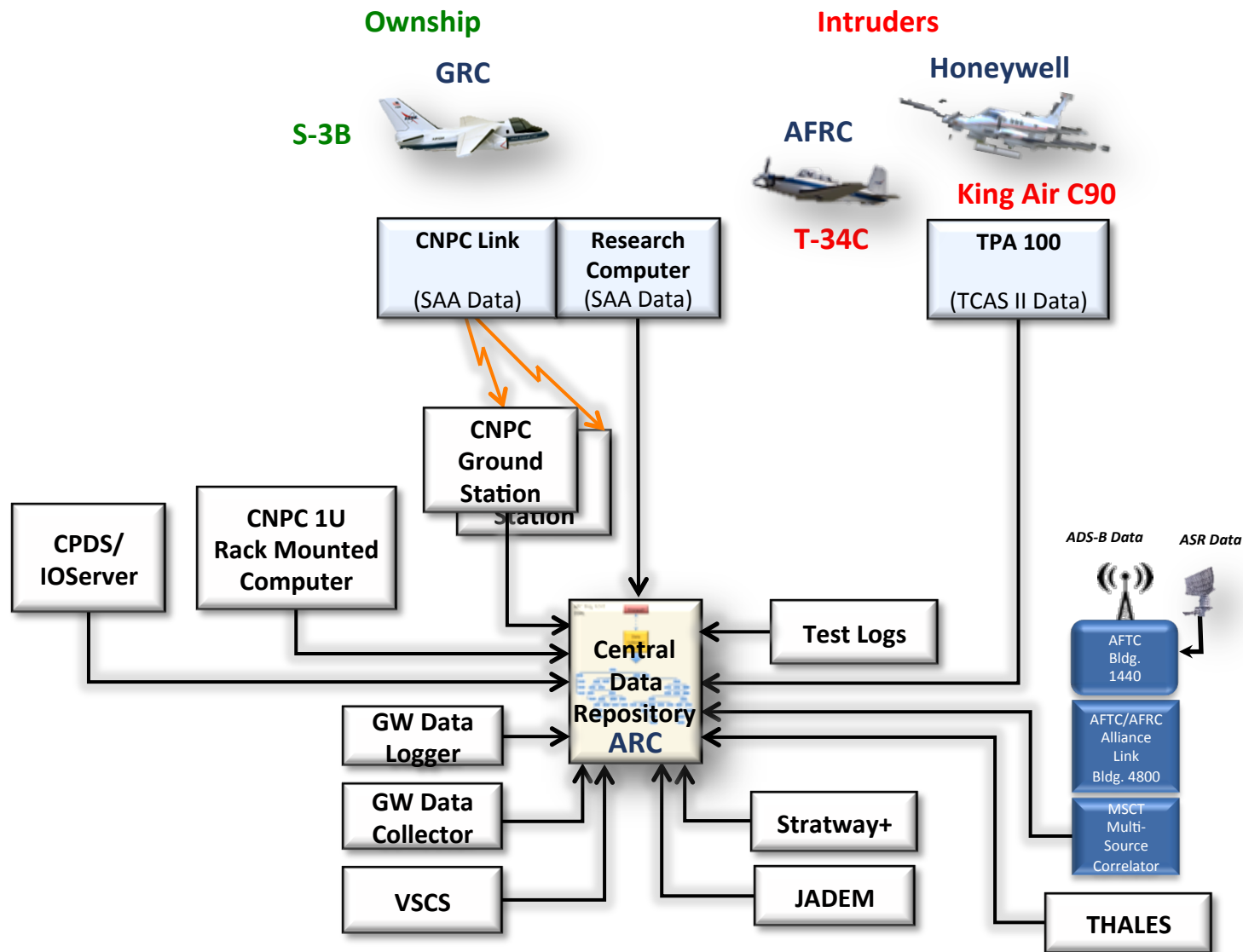


Data Collection – Configuration 1A



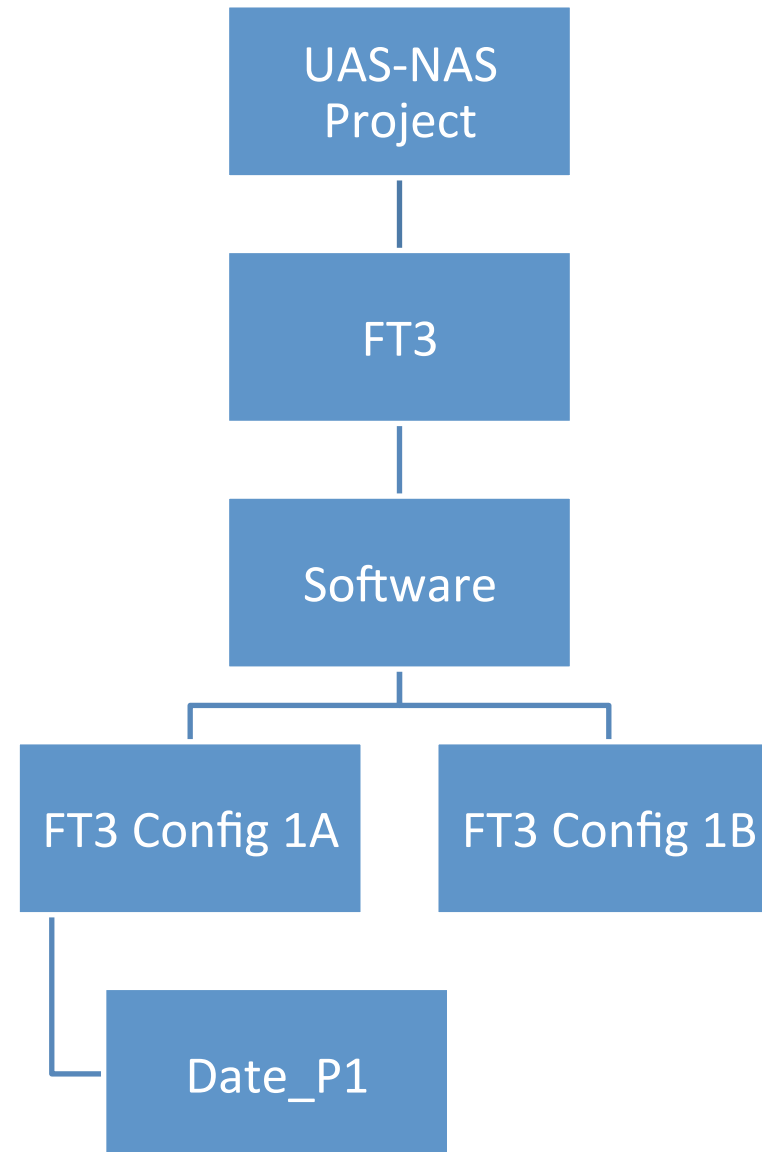


Data Collection – Configuration 1B



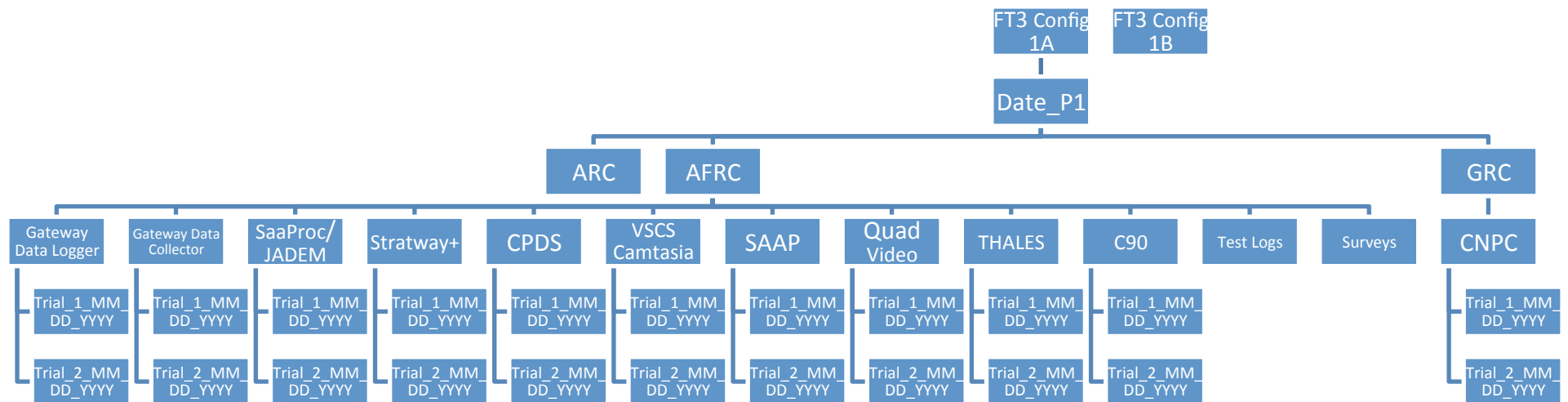


FT3 Directory Structure



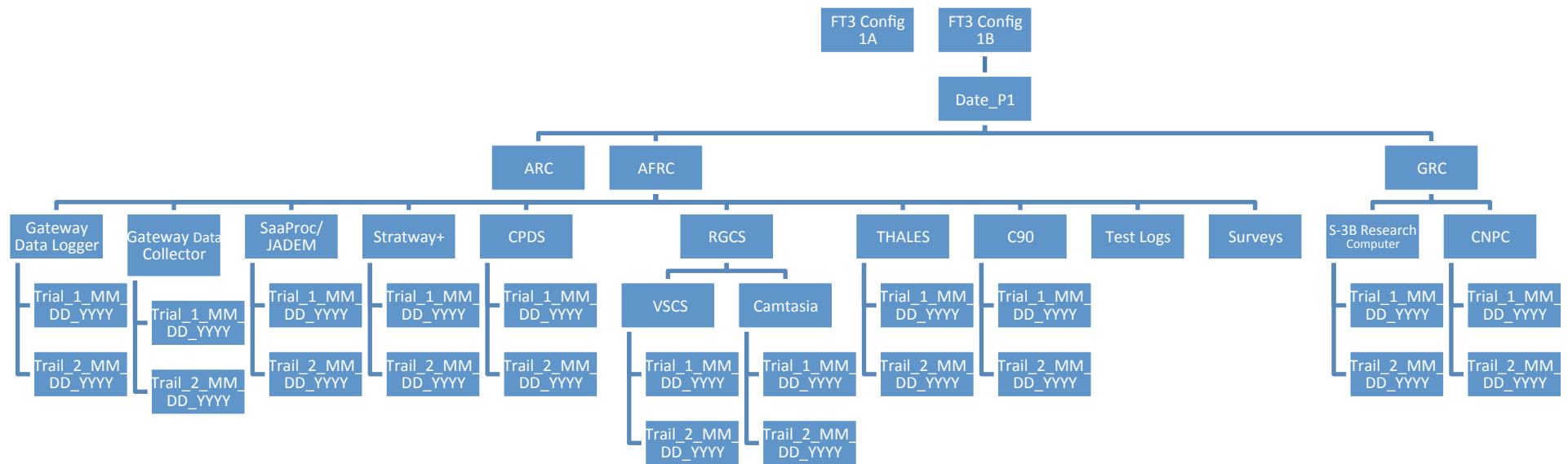


FT3 Directory Structure





FT3 Directory Structure





Flight Test 3 – Configuration 1A/B Voice Communications Architecture

